

## Patient Positioning Using Optical and Ultrasound Techniques

Sanford L. Meeks, Ph.D.

Associate Professor  
Department of Radiation Oncology



## Acknowledgements

- Collaborators
  - University of Iowa
  - University of Florida
  - University of Wisconsin
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## Objectives

### Precision Radiation Therapy

- Optical Tracking in Radiation Therapy
  - What is it?
  - How does it work?
  - How well has it worked?
- Ultrasound Guidance in Radiation Therapy
  - What is it?
  - How does it work?
  - How well has it worked?

## What is Optical Tracking?

- Optical tracking is a means of determining in **real-time** the position of an object by tracking the positions of either active or passive infrared markers attached to the object. The position of the point of reflection is determined using a camera system.



Active markers



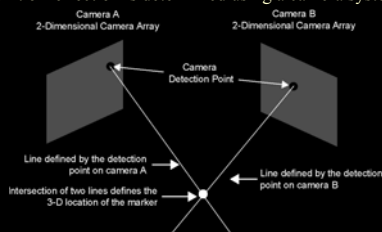
Passive markers



Camera

## What is Optical Tracking?

- Optical tracking is a means of determining in **real-time** the position of an object by tracking the positions of either active or passive infrared markers attached to the object. The position of the point of reflection is determined using a camera system.

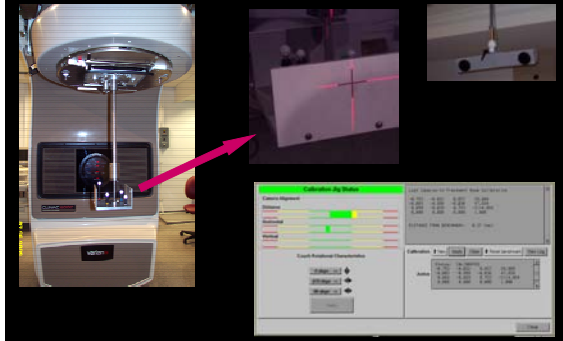


## How Does it Work?

### Optical Tracking



## How Does it Work? Calibration of Optical camera



## Optical guidance for frameless stereotaxis

- For high-precision intracranial radiotherapy and frameless radiosurgery, we use optical guidance to track the actual patient position using passive markers and a bite-plate linkage.



## Frameless Stereotaxis

- Passive Array – Reflective Markers serve as fiducials in both image and real space.

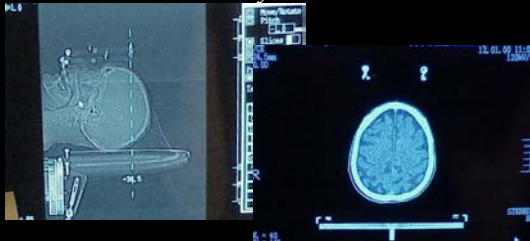


## Frameless Stereotaxis Immobilization During CT Scan



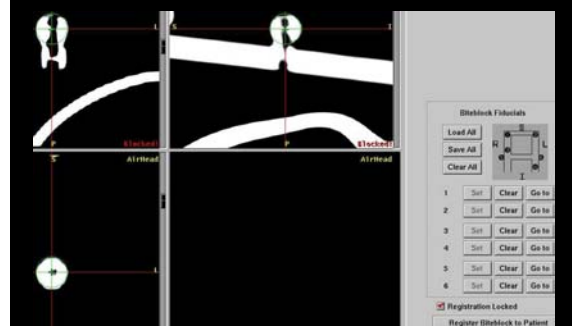
Patients can move – immobilize using custom pillow, aquaplast, etc.

## Frameless Stereotaxis Passive Array – CT Scan



Fiducials must be visible in CT scan – use adequate field of view (typically 35-40 cm depending on distance of bracket from patient).

## Frameless Localization



## Frameless Stereotaxis



Diagram illustrating the transformation of coordinates for frameless stereotaxy:

$$p_i' = R p_i + T$$

Labels in the diagram:

- Vector for room coordinates
- 3x3 rotation matrix
- Vector for image coordinates
- Translation vector

Equation can be solved numerically using optimization algorithms (Hook and Jeeves, etc.), or closed form solutions such as single value decomposition or Horn's method (quaternions)

Diagram illustrating the alignment process for frameless stereotaxy:

Align Patient

Parameters shown on the left:

- AP: 1.1
- LAT: 1.2
- AS: 1.3
- Vector: 1.4
- Couch: 10.5
- Tilt: -0.1
- Spin: -0.1

Parameters shown on the right:

- AP: 0.1
- LAT: 0.2
- AS: 0.3
- Vector: 0.4
- Couch: 0.5
- Tilt: 0.6
- Spin: 0.7

## Optical Tracking – BrainLab System

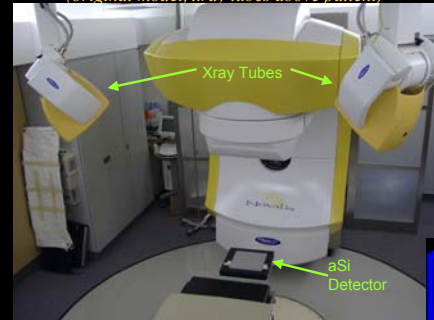


## Optical Tracking – BrainLab System



## X-ray Guidance Setup

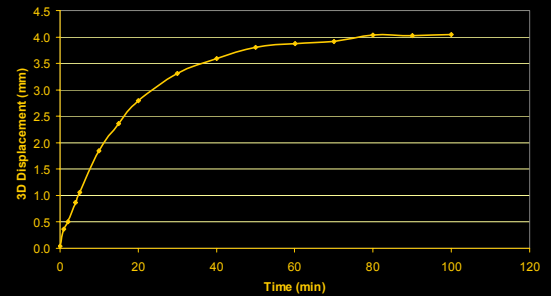
(original model, xray tubes above patient)



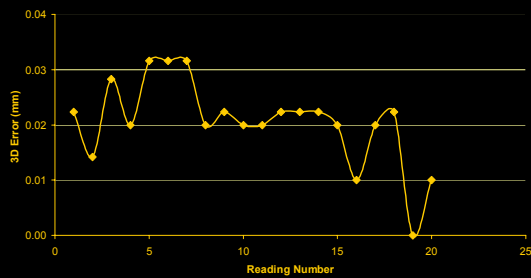
## Optical Tracking System QA

- System Commissioning and QA
- Patient Specific QA

## Thermal Drift



## Reproducibility



## Test with Absolute Phantom

- Localize AI target in images (CT)



## Frameless Localization Accuracy (Mechanical Standard)



## Frameless Localization Accuracy (Mechanical Standard)

No.	AP	Lateral	Axial	RMS
1	0.48	0.48	-0.61	0.91
2	-0.05	0.46	0.50	0.69
3	0.33	-0.20	-0.53	0.65
4	-0.46	-0.15	-0.13	0.50
5	0.43	-0.15	-0.13	0.40

Average

$0.65 \pm 0.17$  mm

## Putting it All Together - Hidden Targets Test with Absolute Phantom

- Localize AI target in images (CT)
- Place on linac using image localized coordinates and optical guidance.



## Frameless Localization Accuracy (Film Tests)

- Localize AI target in images (CT)
- Replace AI target with Tungsten target, and place on linac using image localized coordinates.
- Take films from various gantry and table orientations



## ANALYSIS

Edm.Ansden.Exam				Edm.A			
Isocenter height in mm 1266				AB 0.247° mm to A			
Radius of collimator rotation in mm 425				QT 0.493° mm to T			
Radius of source rotation in mm 1000				Vertical 0.439° mm / p			
Enter the number of film shots 5				Edm.B			
				AB 0.247° mm to A			
				QT 0.493° mm to T			
				Vertical 0.439° mm / p			
				Ball 0.551° mm / p			
				Climbal 0° mm to A			
Predicted error:				Results:			
Z-Pixel Size = 1.25mm				Z: 0.49 mm to T			
X-Pixel Size = 0.703 mm				X: 0.35 mm to A			
Y-Pixel Size = 0.703 mm				Y: 0.50 mm High			
Predicted Error = 1.59mm				<b>Overall error = 0.789mm</b>			

## Frameless Localization (Patient)



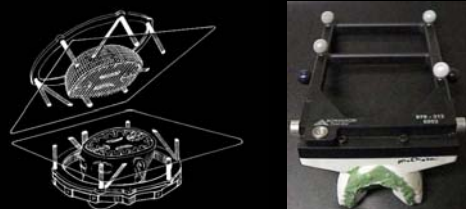
## Frameless Localization (10 Patients)

**Average  $\pm$  s.d. 1.1  $\pm$  0.3 mm**

compared to conventional stereotactic localization

Meeks, Bova et al., IJROBP, 2000

## Can we predict localization errors?



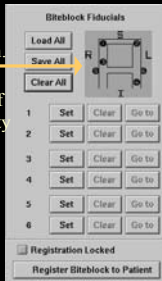
Analogous to frame-based stereotaxis, we have an over-defined fiducial system with a known geometry. Can predict accuracy of patient positioning at isocenter

## Mean Registration Error



Error between CT model and the real array after registration

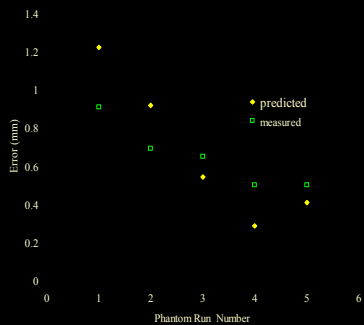
Provides indication of reference array integrity and patient motion.



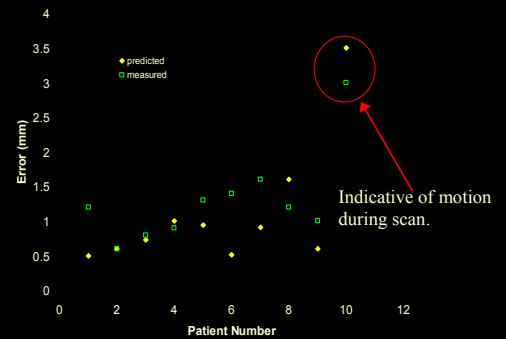
## Frameless Localization (In Phantom)



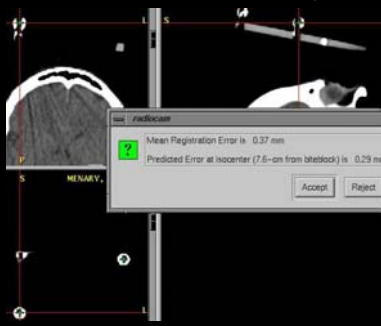
## Mean Registration Error (Phantom)



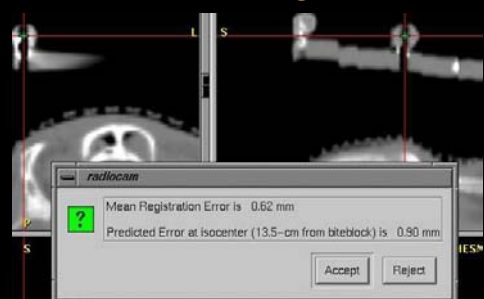
## Mean Registration Error (Patient)



## Frameless Localization (Patient)

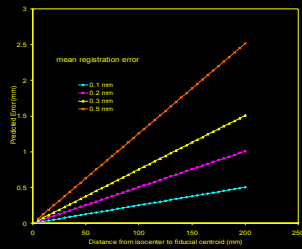


## Motion During Scan





## Array placement



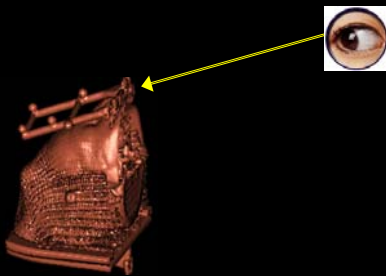
Minimizing the distance from the center of the fiducial array to isocenter minimizes the effect of the mean registration error at isocenter.

## Array placement

Bracket allows adjustment of fiducial array relative to patient



## Array placement



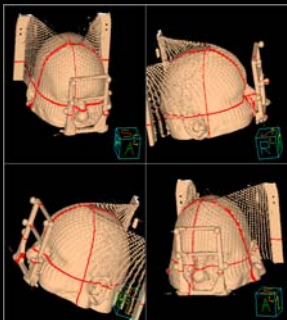
Keep camera "line of sight" in mind – if you rotate too far back, the fiducials will not be visible to the camera in the treatment room.

## Frameless Radiosurgery Reseat Test

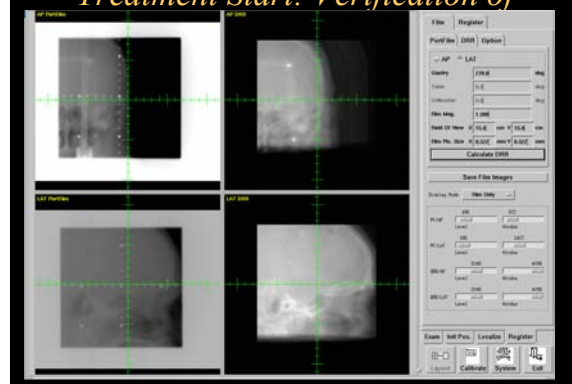


RadioCensus Blockblock Reseat Test Results	
Patient name:	Test
Patient ID:	
Date:	Tue Feb 20 13:27:20 CST 2001
Results:	
Sample # 1	123.042430
Sample # 2	123.047922
Sample # 3	123.043150
Sample # 4	123.076456
Sample # 5	123.009842
Sample # 6	123.149499
Sample # 7	123.000491
Sample # 8	123.117416
Sample # 9	123.051474
Sample #10	123.051720
Average Difference	0.078497
Maximum Difference	0.159073

## Treatment Start: Verification of Setup Using Laser



## Treatment Start: Verification of

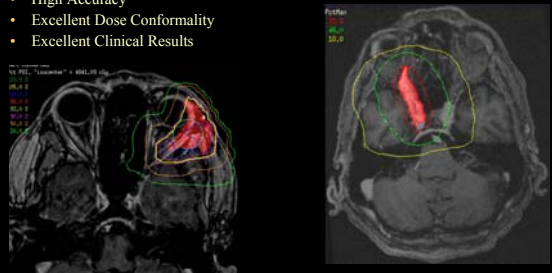


## Online Monitoring of Patient Position during Treatment



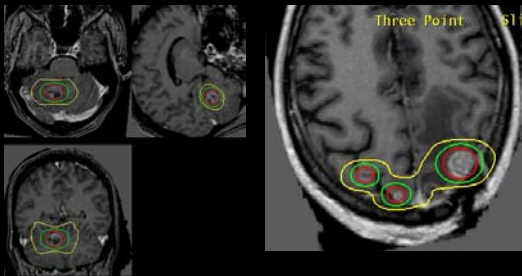
## Optical Guidance in Radiotherapy

- Long-Term Experience
  - University of Florida – started 1994
- High Accuracy
- Excellent Dose Conformality
- Excellent Clinical Results



- June, 2000 – Frameless Radiosurgery – **Why Not?**

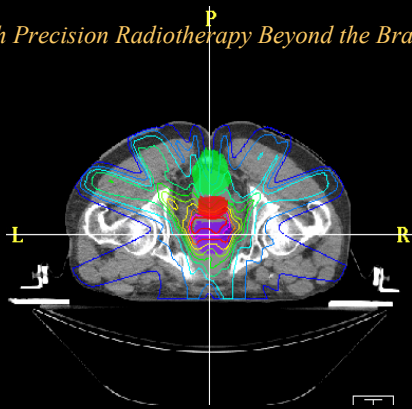
## Frameless Radiosurgery



## Frameless Radiosurgery

- 64 patients with intracranial metastases treated from June, 2000 -September, 2002
  - 1-6 mets (median 2)
  - Rx Dose = 12.5-20 Gy (median = 17.5 Gy)
  - Local Control = 88%
  - Median Survival = 8.7 Months (Max = 30.1 months)
- Results indistinguishable from framed SRS

## High Precision Radiotherapy Beyond the Brain



## Optical Tracking – BrainLab System



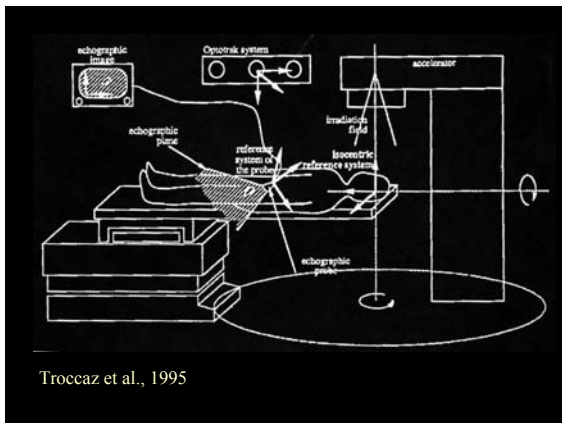


### Diaphragmatic Pressure/Optically Guided Body Frame

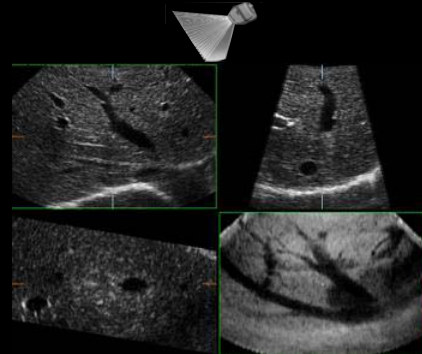


### Extracranial Stereotactic Radiotherapy Solution

- Tumor localization using real-time imaging at the treatment machine
  - Digital X-Ray Images
  - CT
  - Ultrasound



### 3D Ultrasound Imaging



### What is 3DUS guided RT?



High-resolution infrared camera  
Detects passive and active fiducials

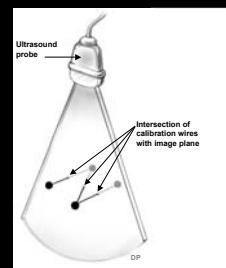
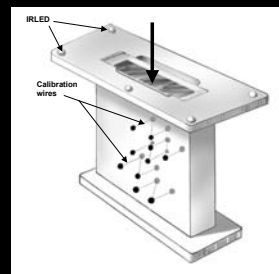
- High-end, Linux custom computer
- Spatial Digitizer linked to Camera
- Image Processing and Localizing Software

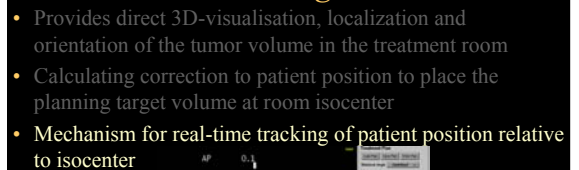
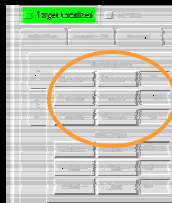
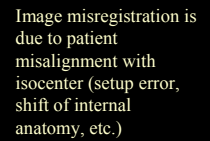
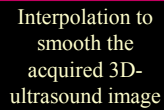
SonoSite Ultrasound:  
- Portable  
- 3.5MHz abd. probe



Optically tracked  
ultrasound probe

### How Does it Work? Ultrasound Calibration





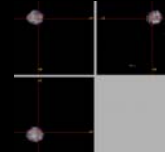
## Ultrasound Guidance QA

W. A. Tomé, S. L. Meeks, N. P. Orton, L. G. Bouchet, F. J. Bova, "Commissioning and Quality Assurance of an Optically Guided 3D-Ultrasound Target Localization System for Radiotherapy," *Med. Phys.* 2002.

## Tracking Accuracy

Using Optical Tracking as Standard

Depth (mm)	AP Distance (mm)	Lateral Distance (mm)	Axial Distance (mm)
All depths	$0.03 \pm 0.4$	$-1.2 \pm 0.4$	$-0.7 \pm 0.5$



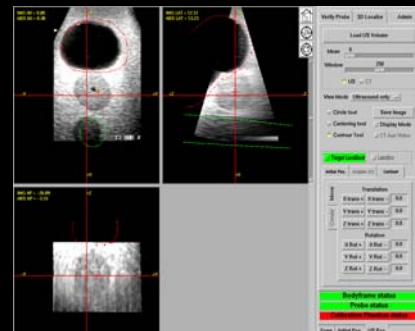
## Pre-Clinical Prostate Phantom Tests

•Using Optical Guidance known shifts are introduced using a translation table.

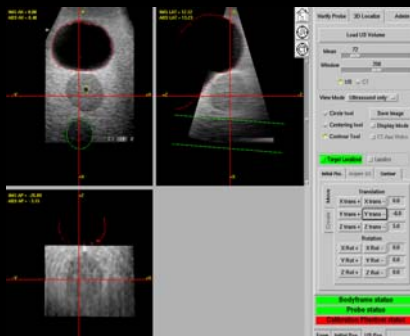
•Optical Guided System is blinded to introduced shifts by recording the position of a fiducial array that is fixed to the couch.



## Optically Guided Ultrasound Target Localization for shifted Phantom



## Contours are moved to Match US Anatomy



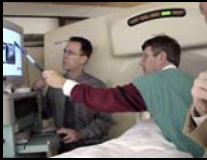
## Results

Exp	AP (mm)	Lat (mm)	Ax (mm)	AP <sub>m</sub> (mm)	Lat <sub>m</sub> (mm)	Ax <sub>m</sub> (mm)
1	0.0	0.0	0.0	$0.6 \pm 0.46$	$-0.3 \pm 0.69$	$-0.03 \pm 0.1$
2	0.0	0.0	5.0	$0.67 \pm 0.52$	$-0.38 \pm 0.61$	$4.95 \pm 0.12$
3	0.0	0.0	-5.0	$0.55 \pm 0.53$	$-0.25 \pm 0.58$	$-5.3 \pm 0.67$
4	0.0	-5.0	0.0	$0.55 \pm 0.53$	$4.95 \pm 0.17$	$-0.22 \pm 0.22$
5	0.0	-5.0	5.0	$0.25 \pm 0.06$	$-5.85 \pm 0.17$	$5.3 \pm 0.27$

W. A. Tomé, S. L. Meeks, N. P. Orton, L. G. Bouchet, F. J. Bova, "Commissioning and Quality Assurance of an Optically Guided 3D-Ultrasound Target Localization System for Radiotherapy," *Med. Phys.* 2002.

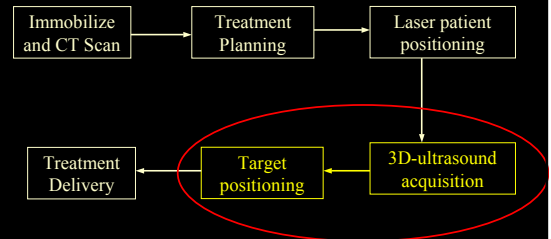
## BAT Tracking Accuracy in Patient Using CT as Standard

AP Distance (mm)	Lateral Distance (mm)	Axial Distance (mm)
$-0.09 \pm 2.8$	$-0.16 \pm 2.4$	$-0.03 \pm 2.3$



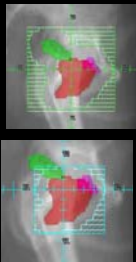
Lattanzi J, McNeeley S, Pinover W, Horwitz E, Das I, Schultheiss TE, Hanks GE. A Comparison of Daily CT Localization to a Daily Ultrasound-Based System in Prostate Cancer. *Int J Radiat Oncol, Biol Phys* 1999; 43(4).

## How Do I Use it Clinically? Basic Process

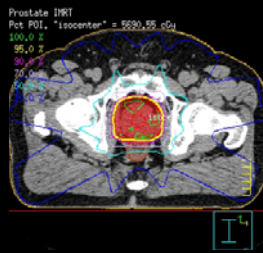


## How Do I Use it Clinically? Treatment Planning

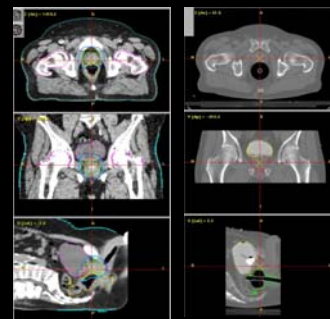
BEV Conformal



IMRT

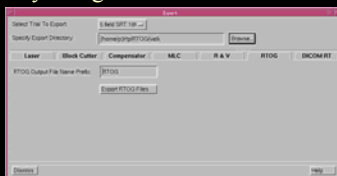


## How Do I Use it Clinically? Treatment Planning

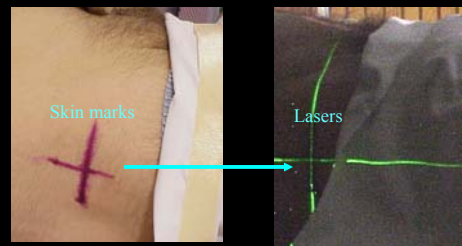


## How Do I Use it Clinically? Treatment Planning

- BEV conformal or IMRT treatment planning using Pinnacle
- CT and structure contours transferred to SonArray using Dicom-RT or RTOG



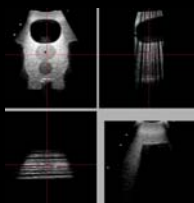
## 3D Ultrasound Image Guidance Initial Alignment from CT Simulation



## 3D Ultrasound Image Guidance

Acquire 3D Ultrasound Data

Analogous to CT acquisition – acquire multiple axial using freehand ultrasound probe manipulation.



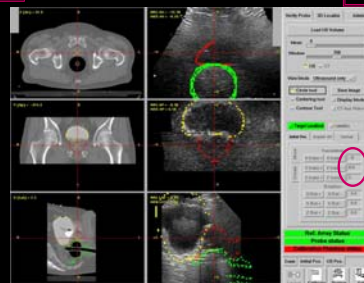
## How Do I Use it Clinically?

CT Images and structures contour from treatment plan

Target Localization

Correlation of 3D-ultrasound image with Treatment Plan

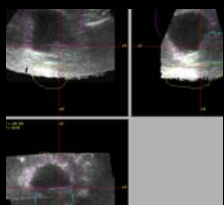
Actual position of target as determined from the 3D-ultrasound



## US/CT Correlation - Prostate

Interface between prostate and bladder

Sem ves  
Bladder  
Nothing below bone!



## How Do I Use it Clinically?

Patient Positioning

AP: 0.1  
LAT: 0.1  
AX: 0.1  
Vector: 0.1  
Couch: 0.1  
Tilt: 0.1  
Spin: 0.1

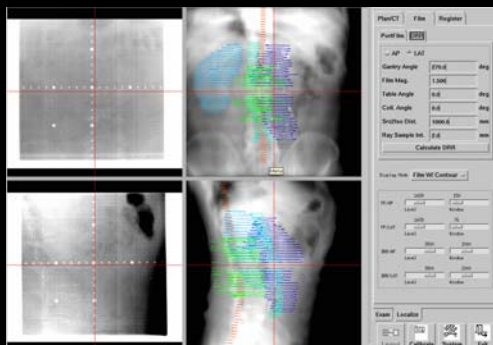
Align Patient



AP: 0.1  
LAT: 0.0  
AX: 0.0  
Vector: 0.1  
Couch: 0.0  
Tilt: 0.0  
Spin: 0.0



## Verify Shifts using Portal Images and DRRs



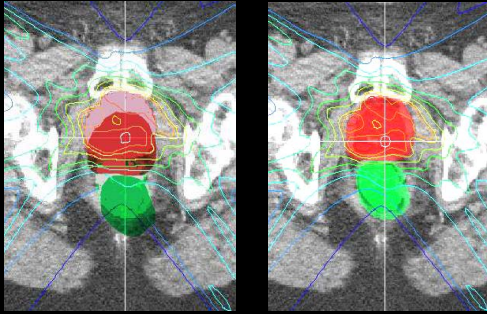
## Proceed With Normal Treatment...





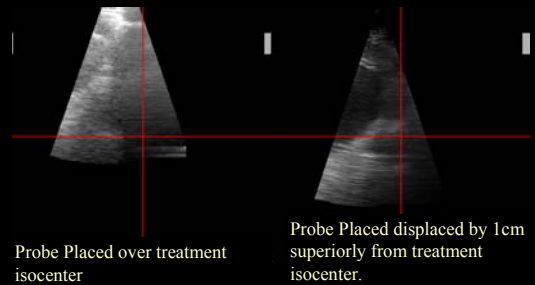
### Pitfalls in Ultrasound Guidance

What happens with inter- and intra-fraction organ motion?



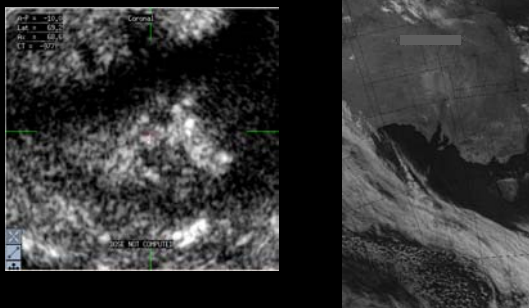
### Pitfalls in Ultrasound Guidance:

#### User Variability in Image Quality



### Pitfalls in Ultrasound Guidance:

#### Ultrasound Interpretation



### Pitfalls in Ultrasound Guidance:

#### User Variability

Retrospective registration of 15 different data sets by 9 different users; 4 users with experience and 5 trained in use of the software, but not US imaging.

#### Average Shift

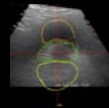
AP (mm)	Lat (mm)	Axial (mm)
3.4	2.7	4.5

#### Std. Dev. (Trained)

AP (mm)	Lat (mm)	Axial (mm)
1.2	0.9	1.4

#### Std. Dev. (Not Trained)

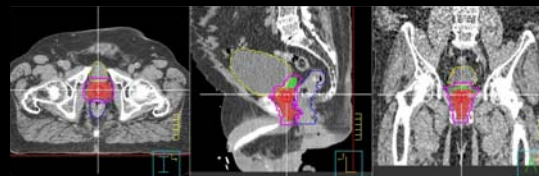
AP (mm)	Lat (mm)	Axial (mm)
3.6	1.5	2.9



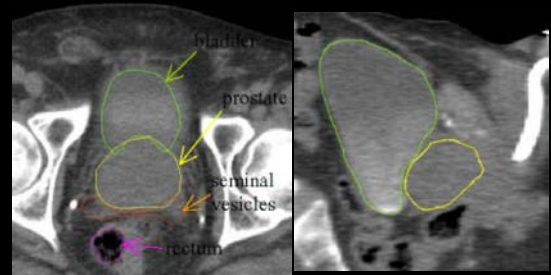
### Treatment Planning

#### US-Guided Prostate

- **Sensible** PTV may be larger than **Minimum**
- Remember user *variability* can vary, which increases required PTV
- In practice, we create a PTV with a variable (5-10 mm) margin on the CTV.

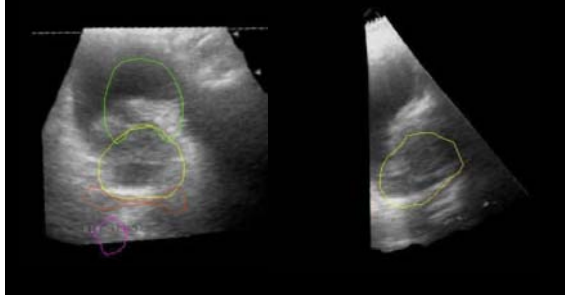


### Work in Progress – Automated Ultrasound Registration

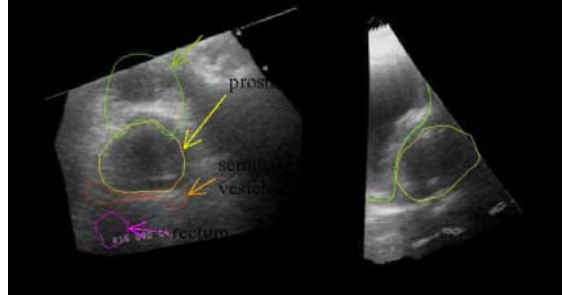




## Work in Progress – Automated Ultrasound Registration



## Work in Progress – Automated Ultrasound Registration



## US-Guided Prostate Trial

- NCI-supported Phase III Randomized Multi-Center Clinical Trial
  - Arm 1 - With ultrasound
    - Initial fields: 46 Gy/23 fractions, PTV = 1 cm margins on prostate, seminal vesicles, and nodes
    - 32 Gy/16 fractions, PTV = 2 mm margin on prostate only
  - Arm 2 - With conventional localization
    - Initial fields: 46 Gy/23 fractions PTV = 1.5 cm margins on prostate, seminal vesicles, and nodes
    - 32 Gy/16 fractions, PTV = 1 cm margin on prostate only

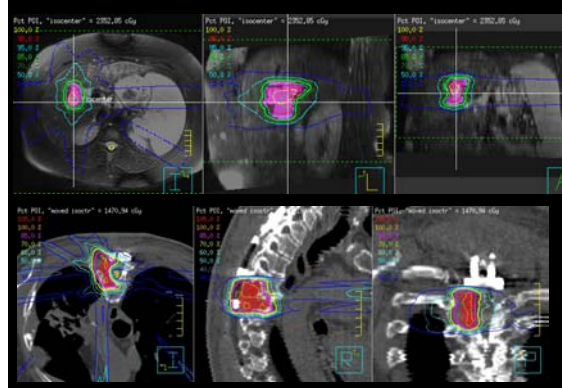
## US-Guided Prostate Trial Preliminary Results

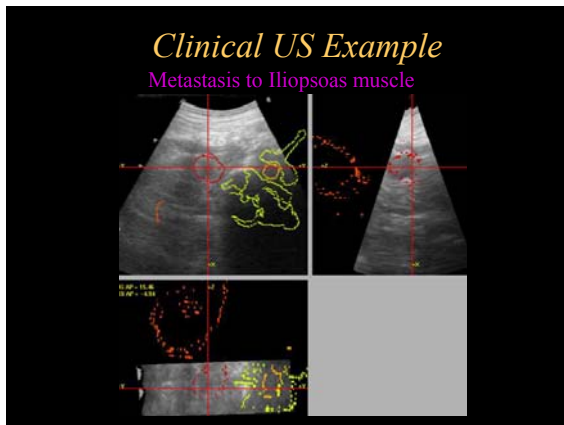
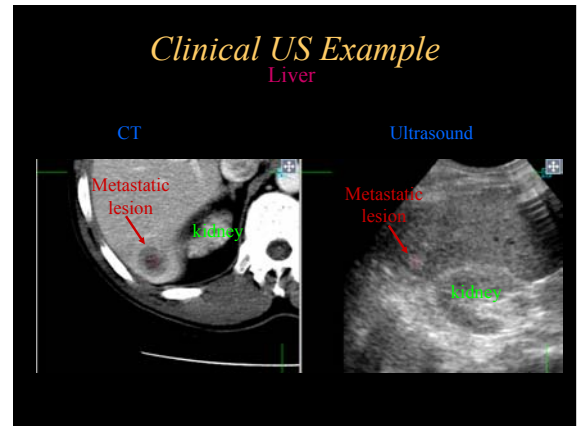
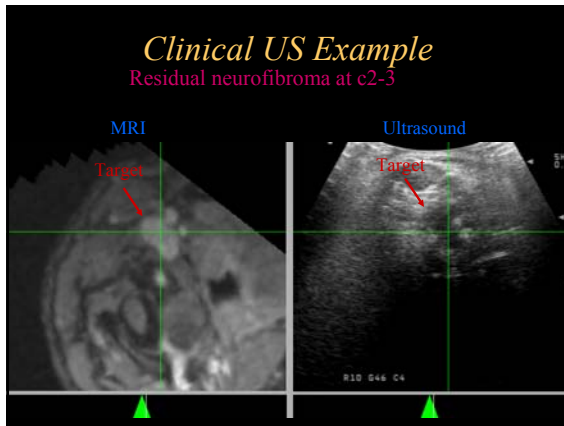
	Acute GI Toxicity			Acute GU Toxicity	
	Arm 1 3DCRT	Arm 2 U/S- 3DCRT		Arm 1 3DCRT	Arm 2 U/S- 3DCRT
<b>Grade 0</b>	25%	89%	<b>Grade 0</b>	50%	66%
<b>Grade 1</b>	0%	11%	<b>Grade 1</b>	25%	33%
<b>Grade 2</b>	75%	0%	<b>Grade 2</b>	25%	0%
	$p=0.014$			$p=0.45$	

## 3D Ultrasound Image Guidance *Other Applications at UIHC (to date)*

- Liver
- Low neck
- Paraspinal
- Metastatic pelvic lesions
- Chest wall

## Extracranial US-Guidance





*Future Development/Questions*

- Reliable Automated image registration techniques – important for all image registration modalities (CT, x-ray, US)
- Technical improvements in organ motion management
- Clinical Trials defining true benefits of image-guidance and IMRT.
- Defining dose/volume tolerances for hypofractionated regimens – Rigorous Phase I dose-seeking studies are required