

## AbstractID: 3752 Title: A Novel Metric for Automatic Assessment of Deformable Image Registration Accuracy

### Purpose:

The purpose of this research is to develop a metric that automatically assesses the accuracy of deformable image registration by evaluating the difference in voxel values and the minimum distance to agreement between the predicted and actual images.

### Methods and Materials:

A metric,  $\kappa$ , has been developed, which is based on two parameters 1) difference in voxel value and 2) minimum distance to voxel agreement. Voxels within the predicted image, or a selected subregion within the region, are randomly selected for evaluation. Each voxel is assessed to determine if it is within 3 image units (i.e. Hounsfield Units or MR number) of the voxel value on the actual image or within 0.3 cm of its corresponding voxel on the actual image. The  $\kappa$  index indicates the percentage of points passing at least one of the parameter.

The correlation between  $\kappa$  and the error in the image was established by introducing known random error into an image. Mathematically deformed CT and MR data was generated for analysis (mean = 0 – 0.5, SD = 0 – 1.0 cm).

### Results:

Although the metric can overestimate the percentage of points meeting the criteria, due to similar voxel values in the search region, a unique correlation was established between the effective error in the image with known deformation and  $\kappa$ . A power law relationship between described 98% of the variance between the known error and  $\kappa$ . This relationship was then used to assess the error in deformable image registration using a finite element based method. The results show good agreement with prior manual accuracy evaluation.

### Conclusions:

A novel metric,  $\kappa$ , describing the error in deformable image registration has been investigated providing a unique correlation between  $\kappa$  and the residual error in registration.

### Conflict of Interest:

This research was supported in part Varian Medical Systems.