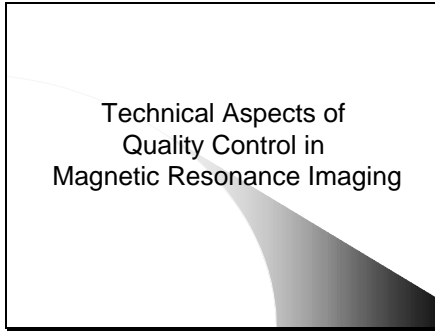


Slide 1



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Slide 2



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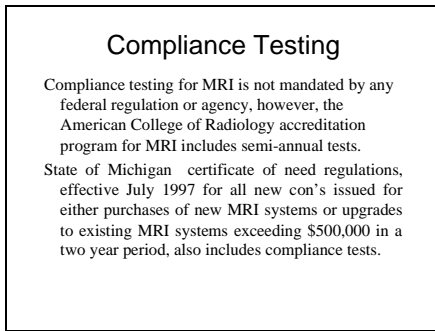
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Slide 3



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Slide 4

**ACR Semi-Annual Test Requirements**

- Review of Daily QC
- Image uniformity
- Spatial linearity.
- Spatial resolution.
- Slice thickness, location, and separation.

ACR STANDARD FOR  
THE PERFORMANCE OF  
MAGNETIC RESONANCE IMAGING

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Slide 5

**ACR Accreditation Test Requirements**

- Geometric accuracy (spatial linearity).
- High contrast (spatial) resolution.
- Slice thickness
- Slice position accuracy
- Image Uniformity
- Percent signal ghosting (phase stability)
- Low contrast resolution.

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Slide 6

**State of Michigan Compliance Test Requirements**

- Signal to noise ratio.
- Spatial resolution.
- Slice thickness, location, and separation.
- Spatial linearity.
- Field homogeneity and drift.
- System calibration and stability.
- Cryogen level and boil off rate.
- Radio frequency power monitor

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Slide 7

**Other Optional Tests**

- Repeat tests for
  - Other Orientations
  - Other FOVs
  - Body or surface coils
- Field homogeneity.
- Display Monitor
- Cryogen Boil off

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Slide 8

**Comparison of Compliance Testing in CT and MRI**

Dose, Scatter Radiation	Review of Daily QC
Uniformity	Image uniformity
Pixel size calibration	Spatial linearity.
High contrast resolution	Spatial resolution.
Slice thickness, overlap	Slice thickness, separation.
Low contrast resolution	Low contrast resolution
CT number for water	T <sub>1</sub> , H <sub>2</sub> O ?, Other?
Contrast scale, linearity	
Noise level	SNR
	Slice Position Accuracy
	Percent Signal Ghosting

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Slide 9

**Why No Accreditation SNR?**

- System Variability
  - Hardware (eg maximum gradient amplitudes)
  - Software (pulse sequence differences/limitations)
- Field strength dependence
- Different measurement methods
- Differences in materials (T1, T2 etc)

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Slide 10

**T<sub>2</sub> as Calibration Standard**

Sensitive to environmental Factors  
 Temperature  
 Concentration of Ions, O<sub>2</sub>  
 Function of System Characteristics  
 Field Strength, Homogeneity  
 Non-Ideal RF pulses  
 Error in T<sub>2</sub> Calculation

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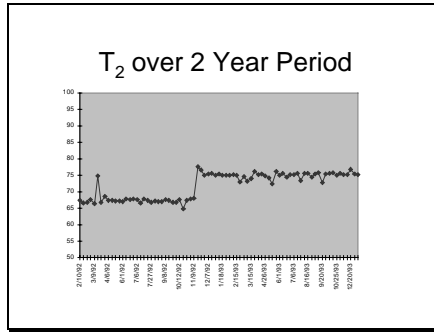
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Slide 11




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Slide 12

**Standard Pulse Sequences**

	<i>T1 Weighted</i>	<i>T2 Weighted</i>
<b>TR</b>	500	2000
<b>TE</b>	20msec	20/80 or 30/90
<b>Matrix</b>	128, 160, or 256	128, 160, or 256
<b>Coil</b>	Head	Head
<b>#excitations</b>	1	1
<b>FOV</b>	24or 25	24 or 25

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Slide 13

**Image Uniformity**

The degree to which MRI of a homogeneous test object results in a uniform image response across the FOV of the object.

An MR image acquired from any coil has some degree of non-uniformity. This non-uniformity will be more or less evident depending on the window and level used to display the image.

It is necessary therefore to use a criterion that is quantifiable and independent of the means used to display or print the image.

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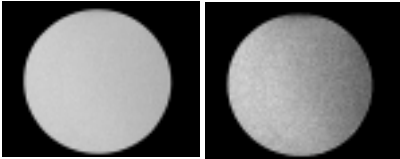
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Slide 14

**Uniformity Narrow vs. Wide Width**



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Slide 15

**Image Uniformity (cont.)**

Image uniformity is influenced by

- Main magnetic field homogeneity
- RF non-uniformity
- Gradient linearity
- Eddy currents
- Pulse sequence type

Test objects also influence image uniformity

- Magnetic susceptibility
- RF penetration

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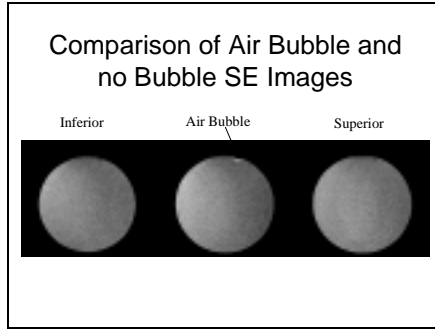
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Slide 16



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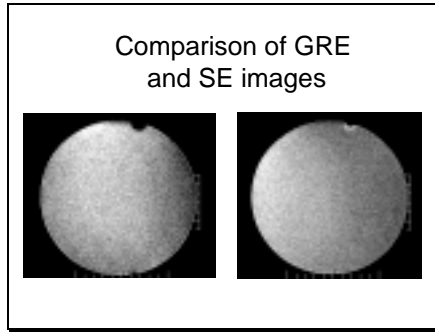
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Slide 17



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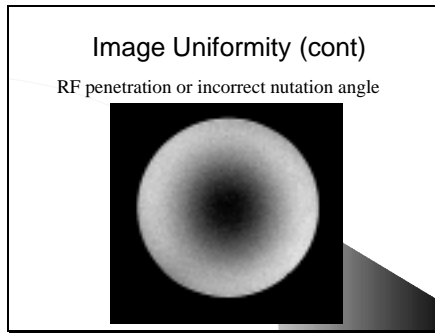
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Slide 18



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Slide 19

**Image uniformity (cont.)**

**Test object**  
 Diameter ≥ 80% of routine FOV used for RF coil.  
 Conductivity such that RF penetration similar to tissue.

**Coils: Head, Body**

**Example imaging parameters**  
 Std. T1 Weighted  
 Single echo, single 10mm slice  
 Single excitation  
 FOV > 80% of coil dimension or largest used clinically

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Slide 20

**Image uniformity (cont.)**

**Procedure**

**Uniform Spherical Phantom**  
 Acquire image in all three orientations centered at isocenter in the magnet.

**ACR Phantom Slice #7 - Axial Plane only**

Measure mean,  $\sigma$ ,  $S_{max}$ , and  $S_{min}$  from an ROI centered on and enclosing at least 75% of the image

Exclude regions near boundaries of the test object  
 Inspect for evidence of air bubbles. Avoid placing ROI near air bubbles.

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Slide 21

**Image uniformity (cont.)**

Calculate the percent integral uniformity:

$$PIU = \left[ 1 - \frac{S_{max} - S_{min}}{S_{max} + S_{min}} \right] \times 100\%$$

**Action level**  
 Should meet manufacturer's specifications > 90%

**If test fails**  
 Examine ROI for hot spots and repeat analysis using ACR accreditation recommended procedure

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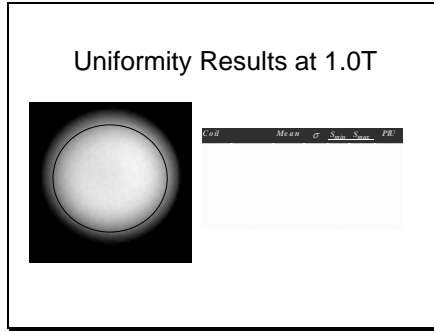
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Slide 22



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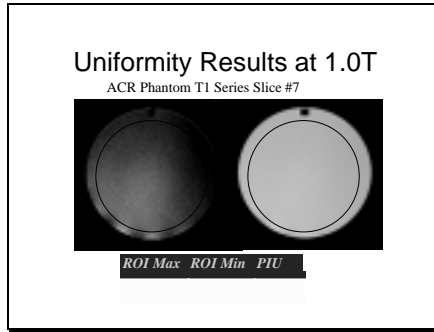
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Slide 23



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Slide 24

**Spatial Linearity**

The degree to which the MR image response accurately reflects the spatial location from which the signal originated.

Factors which influence spatial linearity are those which modify  $B_{tot}$  and signal phase and frequency in any location in the FOV:

- Magnetic field homogeneity
- Magnetic susceptibility
- Gradient linearity

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Slide 25

**Spatial linearity (cont.)**

Test object  
Any object for which accurate dimensions are known, provided that magnetic susceptibility effects are minimal.

Acquire standard T1 weighted image in  
Each orthogonal plane  
Optionally acquire images swapping phase and frequency directions.

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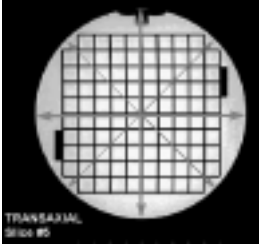
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Slide 26

**ACR Spatial Linearity Insert**



TRANSAXIAL  
Slide #0

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Slide 27

**Spatial linearity (cont.)**

Measure distance of object in both inplane directions.

Procedure for determining object boundary

Method 1: If the computer possesses profile analysis, measure profile across entire test object and measure distance between FWHMs at each end.

Method 2: Determine the mean signal within an ROI containing = 75% of test object and within adjacent outside area but not containing boundary pixels. Set window width to one and the window level to the midpoint between the these two values. Measure distance in this binary image.

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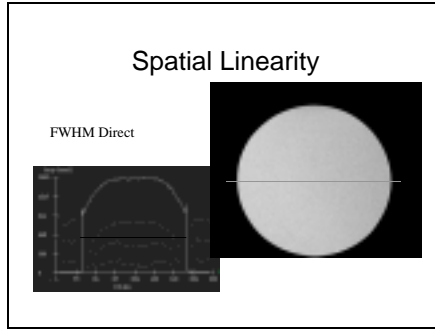
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Slide 28




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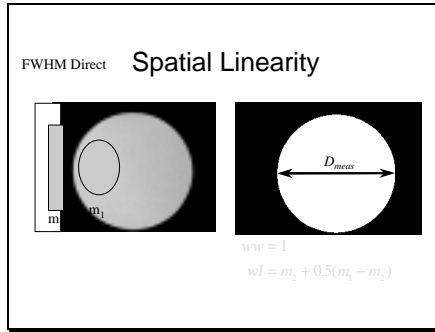
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Slide 29




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Slide 30

**Spatial linearity (cont.)**

Calculate the percent geometric distortion.

$$GD = \frac{D_{tr} - D_{meas}}{D_{tr}} \times 100\%$$

Action level:  
 GD should be < 5% across the FOV, and generally < 2%.

Alternatively, if using the ACR phantom, measured lengths should be within  $\pm 2$  mm of their published values.

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Slide 31

**Spatial Resolution**

The ability of the MR system to resolve high SNR and CNR objects depends on:

- Gradient strength
- Data sampling strategy (matrix)
- Reconstruction algorithm, signal processing

Minimum resolution is pixel limited, i.e. minimum object size = pixel size.

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Slide 32

**Spatial Resolution (cont.)**

Spatial resolution is most completely characterized by the point spread function, however, determination of the PSF can be time consuming. Measure spatial resolution analogous to CT ,i.e., visual evaluation of test objects.

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Slide 33

**Spatial Resolution (cont.)**

Analogous to CT the high contrast resolution insert consists of a regular array of alternating holes and spaces of varying diameters. In this case 3 blocks of holes with spaces equal to the respective hole diameters of 0.9, 1.00, 1.1 mm, were drilled in a 11mm thick bar. Holes were drilled in two orthogonal directions in the test object to permit simultaneous estimation of resolution in both frequency and phase encoding directions.

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Slide 34

**Spatial Resolution (cont.)**

Test object positioning  
Position insert at isocenter  
Line reference guides to insure axis of phantom is perpendicular to scan plane.

Procedure  
Utilize ACR Accreditation T1 and T2 Series Slice #1  
Magnify image 2-4 times  
Record smallest hole pattern visible in both directions using predetermined window level and width method.

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Slide 35

**High Contrast Resolution**

Resolution Insert No Filter	ACR Phantom Slice #1
	
Filter 1	
Filter 2	

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Slide 36

**Slice Thickness**

In MRI, the slice thickness depends on  
gradient strength and linearity  
magnetic field homogeneity  
RF homogeneity  
pulse sequence type (e.g. 2DFT vs. 3DFT)

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Slide 37

**Slice thickness (cont.)**

Two methods for slice thickness measurement  
Measure slice profile directly by applying slice and frequency gradients in slice direction  
Profile across image directly measures slice thickness  
Image a ramp oriented perpendicular to scan plane

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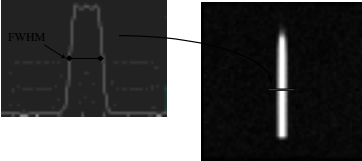
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Slide 38

**Direct image of Slice Profile**



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Slide 39

**Slice Thickness (cont)**

Method 2 ramp angled wrt image plane  
Scan parameters  
ACR T1 Series, Slice #1  
ACR T2 Series, Slice #1  
Scan test object position  
Center of slice at isocenter, making sure that phantom is aligned in all three dimensions.

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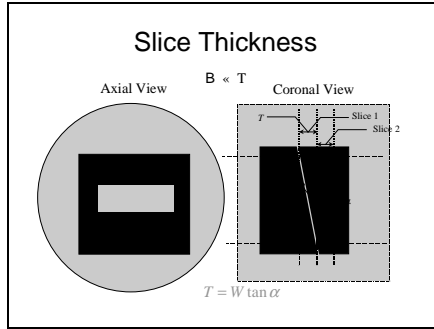
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Slide 40



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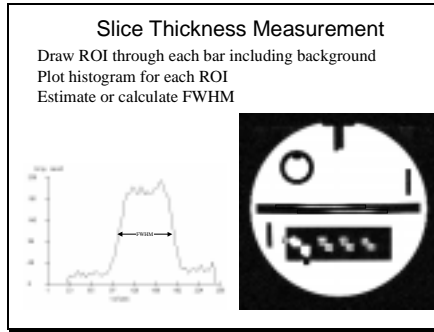
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Slide 41



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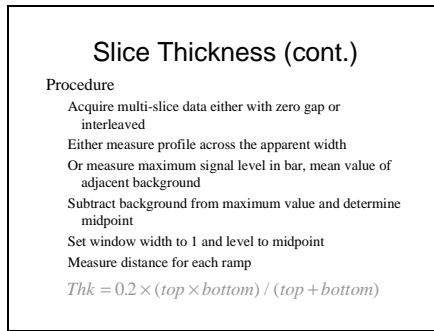
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Slide 42



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Slide 43

**Slice Separation**

Using the multi-slice image set acquired for slice thickness, add adjacent slices.

Image of bar should be twice the width of a single slice.

Note any gaps or central region of double signal intensity.

Action level: gap, or overlap should be 1 mm or less.

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Slide 44

**Slice Separation**  
Add adjacent slices

The diagram illustrates two scenarios for adding adjacent slices. On the left, labeled  $B < T$ , a square represents a slice with width  $B$  and thickness  $T$ . A diagonal line indicates the slice's orientation. On the right, labeled  $B = T$ , two such squares are shown overlapping. The overlapping region is labeled 'Overlap'. The diagram shows how the slices are positioned relative to each other when their width is less than or equal to their thickness.

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Slide 45

**Summed Separation Images**  
4mm Thickness with 0 mm gap

The slide shows two rows of images labeled 'Slice 1' and 'Slice 2'. Each row contains two circular images of a bar. To the right is a graph with a vertical axis labeled 'High Signal Side' and a horizontal axis. The graph shows a step-like signal profile. A note points to the center of the ROI, stating: 'Note no gap or overshoot in center of ROI'. A small 'M' is visible at the bottom right of the graph area.

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Slide 46

**Phase Stability**

All current MRI imaging methods use phase information for spatial localization. Some techniques employ additional phase shifts to encode other information into the MR signal (e.g. phase contrast angiography). From conventional 2 DFT to single shot EPI, MR imaging methods require multiple data samples in which the phase is incremented in a precise fashion.

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Slide 47

**Phase Stability**

The reconstruction algorithm assumes that the phase is stable between samples and that any phase shifts are accounted for. Unwanted phase shifts produce spatial misregistration which appear as faint copies of the image displaced along the PE axis. These phase shifts may be produced by tissue motion during application of gradient pulses, or may be due to drift or failures in RF or gradient subsystems.

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Slide 48

**Phase stability (cont.)**

Method 1: Percent Signal Ghosting  
Use ACR Phantom Slice #7, T1 Series  
Draw large ROI (> 200 cm<sup>2</sup>) in center  
Draw 4 ROIs in phase and frequency noise regions  
Record mean signals. Ghost Ratio is

$$GR = \frac{|(top + bot) - (left + right)|}{2 \times LROI}$$

Action Level: G.R. ≤ 0.025

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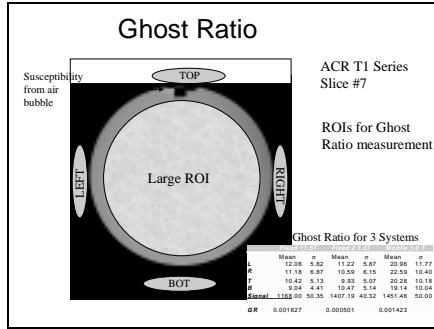
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Slide 49




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Slide 50

**Phase stability (cont.)**

Method 2

Test object  
Uniform sphere or cylinder, diameter < 0.5 FOV.

Position  
Displaced from isocenter in both frequency and phase encoding directions

Pulse sequence  
Multislice TR 2000, TE 20,80  
– One excitation

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Slide 51

**Phase stability (cont.)**

Acquire multiecho, multislice data  
Inspect all slices and echoes for evidence of ghosts  
Record image number, position, of image with maximum intensity ghosts  
Measure mean value from an identical ROI in original image and ghost image

$PE = (\text{Mean}_G / \text{Mean}_O) \times 100\%$

Action level  
Mean signal from ghosts should be less than 2% of original image signal.

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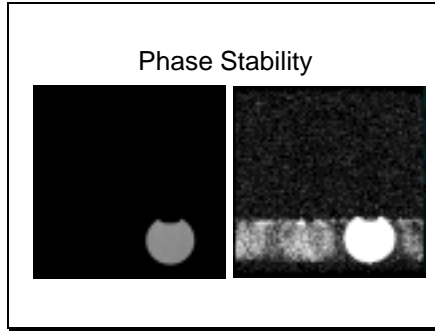
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Slide 52



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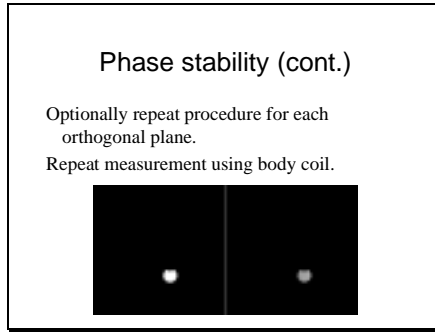
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Slide 53



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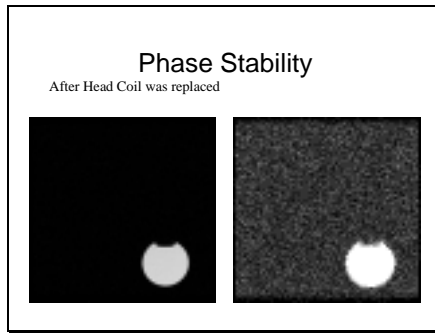
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Slide 54



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Slide 55

**Summary**

Compliance test result influenced by  
    Test Object , Pulse Sequence, Anatomic Plane  
Measure relative changes, not absolute limits  
Optional methods for  
    Data Acquisition  
    Data Analysis  
Total imaging time 1-1.5 hours if using  
    several phantoms and/or multiple planes  
Analysis time in addition to image acquisition

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