

AbstractID:8 597 Title:Monitoring and Quality Assurance of the Tomotherapy Hi-Art using the build-in MVCT detector

#### **Purpose**

Monitoring the Helical Tomotherapy (HT) machine using the signals from the system's built-in Megavoltage CT-detector (MVCT), leading to a filmless Quality Assurance (QA) program

#### **Methods and Materials**

Four monitoring tools are developed in the RISO which are in use for both HT machines, since May 2007:

- TomoOutput: for daily measurement of output and energy.
- TomoScope: provides a 30 Hz graphical representation of the operational status of the machine, while radiating.
- TomoPhysics: provides both pulse-by-pulse analysis and at end-analysis of the transverse profile of 18 different machine parameters and combinations from that.
- TomoQA: automates QA, using an AI-step wedge phantom.

#### **Results**

A number of parameters are monitored daily, like water-flows, air-pressure, water-temperature, CT-channels and monitor-chambers. The transverse profile is tuned within typically 2%. Drift in the target degradation. Output shows a variation of 0.8%. Drift in dose rate is 0.9%/200sec for one HT and 0.3%/200sec for the other. Geometric stability as a function of gantry position is excellent: top-top 0.5 CT-channel.

The QA tool results (sept'07 - feb.'08): The longitudinal profile FWHM 1.0 mm varies 0.05 mm ( $1\sigma$ ). Energy varies 0.2% ( $1\sigma$ ). Synchronization of MLC-gantry varies 0.2 deg ( $1\sigma$ ). Couch speed varies 0.2% ( $1\sigma$ ). After started procedure should closely align the interrupted one. Small mismatches of 0.2 mm are measured ( $1\sigma$ ). Stability of the sagittal and transverse laser is good ( $\sigma=0.4$  mm).

#### **Conclusions**

The monitoring tools have increased our understanding of the behaviour of the merging treatment modality. The QA tool is time efficient because the analysis is filmless and addresses several simultaneous. We aim to run the procedure on a daily basis. The wQA program is simple and based on the set-up and experiences. This program is in use since September 2007. Future functionality will incorporate gantry behaviour and MLC dynamics.