AbstractID:9248Title :Im provementsf orfullyautoma ticlungsegmentation fr om RT planningscans

Purpose: Segmentation of pulmonary X-raycomputed to mography(CT) im agesisap rimordial step tomostpulm onaryimag eanalysisapp lications. Manyap proachesh avebeen presented in the past mainly f ocusing o n lun g extraction f rom h igh reso lution C T d ata. L ooking towards RT planning one has often to deal with low imag equality, artif acts and p athological chang esoft he anatomy. W e present a fully au tomatic method for delineation of the lungs and the trac hea in three-dimensional RT plannings cans for tho rax and br eastpatients.

Method an d Materials: The method consists of several steps. First, lun greg ion is extracted automatically computing an optimal th reshold method. Then, the trachea is s eparated from the lungs by fast marching. Next left and right lungs are separated in each slice by computing a minimal path in the area where s eparation is suspected from the einformation of then eighboring slices. Finally the 3D segment tations of the left and right lungs are refined running the random walker algorithm with foreground and b ackground seed s automatically calculated from the intensity-based pre-segmentation.

Results: Processingtime is below one minut eand d oes not require any user input. Several 3D CT Datasets from different platients were used to evaluate the methods. The algorithms can segment the tracke aan dsep aratethele ftand right lung. I ncom parison top revious publications stability could be used to evaluate enots at signing, e.g. trackea segmentation reaches into the lungsan dl esions or emphysema are not in cluded in the lung segment tations.

Conclusion: The presented al gorithmallows for f ully au tomatic lungs egmentation. One major improvement could be to emp loy a shapemod elas recently published by oth erg roups as a shape-constrained segmentation method could help to overcome the observed problems with exclusion of pathologies.