Purpose: To assess the geometrical uncerta inty caused by the prosta te rotational motion in radiotherapyandits'e ffectonthetrea tmentmargin ca lculation.

Method and Materials: Prostate rotation angle relative to the position in the planning CT is reported dail y by the Calypso 4D Localization System (Calypso Medical, Seattle, WA) basedo nthe detected transponders' locations. The contour for the clinical target volum e(CTV) was obtained from the planning CT ima gea nd was smoothed firs to remove the jitt erscaused by the uncertainty of the de lineation. A fter the CTV c ontour was rotated by a Calypso system reported degree around the isocenter, distances from the points on the rotated contour to the original contourw ere then calculated. The prostate was treated as arigid body in the calculation and thus the deformation angles of ten treatment fractions for tw enty patients, the statistical result softhe geometrical uncertainty caused by yrotation, such as the emean value and standard deviation of the esystematic error and the standard deviation of the randomerror were then calculated.

Results: The prostate rotation detected at the setup time for the twe nty prostate patients has a mean value of 6.4 degrees and a standard deviation of 4.4 degrees. The maximum rotation angle is 2.7 degree. The stand and deviations for the systematic error and the random error of the geometrical uncertainty are a bout 1.3 mm and 1.7 mm, respectively. The mean value of the systematic errors is about 2.5 mm and 2.5

Conclusions: Geome trical unc ertainty ca used by prostate rotational motion was estim ated quantitativelybasedonthe d etectedr otationangles. Its'e ffectontre atmentmargincal culationis significant.