AbstractID:9434Title:Simul ationofin trafractionmo tionan do verallge ometrical accuracyof aframe lessin tracranialra diosurgeryp rocess

Purpose:

Evaluate the clinical ac curacy of a ni mage-guided frameless in tracranial radio surgery syst emincluding the positioning a ccuracy of the 6DEx acTrac System. Anove lmethod was evaluated to prospectively determine an optimal PT Vm argin.

Methoda nd Materials:

Theove rall systemis ocentrica ccuracywast estedwi thari gidanthropom orphicphantomcont ainingahiddentarget. A dditionally, a Rando®Phantom wa sutilized fortest ingtheposit ioninguncertainti esinthe6DE xacTracSyst em wheret iltsandr otationswere physically appliedandth enadjustedbytheRobot icTa bleTop andExacTrac Software. Intrafractionmotion wassi mulatedinfi ve healthyvolunt eers immobilizedwithh eadandshoul dersre inforced thermoplasticmask s.T hesubjectswer ep lacedi na t reatment position or 15minutes (the emaximum expect edtime between repeated isocen terlocal izations) and thesix -degree-of-freedomtar get displacementswererec ordedwith high frequency by racking infrared markers. The markers were placed on acusto mized pi eccof thermoplastics ecured to the eadindependently of their mobilizationmask.

Results:

Thehidden targettestconf irmedovera llsyst em isocentricaccuracyof $\leq 1m$ m (total3Ddispl acement). Thefi nalaccuracyofth e rotationalsetupofthe cranialisocen terwas 0.14 ± 0 .09de greesYaw, -0.33 ± 0.17 de greesRolla nd -0.43 ± 0.08 degreesP itch. The subjectse xhibitedd ifferentpa tternsandrangeso fheadmoti onduringth emocktr eatment. Thetotaldisplacementvect or encompassing95% ofth ep ositional pointsvaried f rom 0.4to2.9 m m.

Conclusion:

Pre-planningmot ionsimu lationw ithopticaltracki ngwast ested onvol unteersand appearsprom ising for determination of patient-specific PTV margins. Fur ther patient study is necessary and is planned. In the meantime, sy stem ac curacy is sufficient for confident to linicalus ewith 3mmPTVmargins.