## AbstractID:9648T itle:Optim alne edlinga ndse edimpla ntpatternsin pro statebrach ytherapyfor multichannelroboti csyst em

**Purpose:** It is important to find optimal needling and seed delivery patterns that are commonly practiced in the clinics, for developing a mult ichannel robotic brachytherapy system. In this study, different techniques and type s of ne edling and seed implant patternshavebe eninvestigated and a robotics ystemhas been designed.

**Materials and M ethods:** Atotalof 135 prostate cancer patient cases of perman entseed im planthaveb eeninve stigated in this study. These cases are from three different university hos pitals where the types of seeds (radio-isotope, activity, construction), needles, surgical techniques, clinicians and patient population are different. Randomly selected 9.5 patients from hospital -1 were treated with Pd -103 isot ope (2.02m Ci/seed, fre e/loose configuration, automatic genetic a lgorithm optimization-PIPER); 20 patients from hospital -2 were treated with I -125 isotope ( $0.64\pm0.06m$ Ci/seed, lin ked seed, ma nual optimization, Varian-VariSeed-v7.1), and the remaining 20 cases f rom hospital -3 wer et reated with H -125 isotope (0.41mCi/seed, pre -loaded nee dle, manual optimization, Varian-VariSeed-v7.1). N eedle and s eed dis tributions were statist ically a nalyzed to determine o ptimal needle configuration s.

**Results:** Hospital-1 (n=95) : pr ostate volume=  $32.4 \pm 12.3$ cc (range= 15.1-59.8cc), needles=  $23.4\pm4.6$  (range=11-40), seeds=  $82.2\pm21.3$ (range=26-164). Hospital 1-2(n=20) : pros tatevolu me= $36.5\pm14.6$  cc( range=18.2-60.1cc), needles= $14.9\pm2.5$ (range=10-18), seeds=  $51.1\pm10.8$  (range=35-68). Hospital -3 (n=20) : prostate volu me=  $30.9\pm8.2$ cc (20.3-51.5), needles=  $13.6\pm2.6$  (range=10-22), seeds=  $75.7\pm14.8$ (range=56-115). Ther elationshipsbetweennumb ero fse edsan dnu mber ofne edlesappe ared to bemore linearfor cases with Pd -103(fr ees eeds) and I -125(linkedseed s), while mores cattered istribution wasfo und for I -125 with pre -loaded needle s. However, in all cases needles were more or less periphe rally distributed to avoid excessive dose to ure thra.

**Conclusions:** Resultsre vealed tha t16 or les snumber of needle sarranged ma in ly peripherally can be su fficient to cover most of the p rostate seed i mplant c ases with I-125 s eeds; c ases with Pd -103 may require more needles. This information has b een translated for designing a multichannel robotic system.

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