

AbstractID: 11061 Title: Ordinary Least Squares and Partial Least Squares for Intra-Fraction Lung Tumor Motion Modeling

Purpose:

For accurate operation, real-time tumor tracking devices for radiation therapy require the real-time position of the radiation target. In this study, we assess Ordinary-Least-Squares (OLS) and Partial-Least-Squares (PLS) modeling methods for inferring intra-fraction motion from external markers.

Method and Materials:

We obtained the concurrent 3D positions of three optically tracked external markers affixed to the skin and the 3D centroid position of a set of three internal fiducials implanted in lung tumors localized with fluoroscopy by the Cyberknife system. We analyzed 134 treatment fractions from 63 patients, each including 40-112 (mean=62) samples spaced at approximately 1-2min. For each fraction, we used a randomly selected subset of N (4-35) points to train OLS and PLS models to infer tumor motion from the positions of the optical markers, and we repeated this process 40 times for each fraction and each N . We then tested the models against the remaining datapoints in that fraction to determine the position error.

Results:

The PLS mean(\pm standard deviation) errors decreased monotonically as N increased, from 0.3 ± 2.6 cm at $N=4$ to 0.2 ± 1.4 cm at $N=35$. In contrast, the OLS error peaked (mean=5.3cm) at $N=10$ training samples, a consequence of the Moore-Penrose pseudo-inverse regression technique. OLS errors at $N=4$ and $N=35$ were 0.4 ± 4.6 cm and 0.2 ± 1.7 cm, respectively. PLS and OLS mean and maximum errors converged for large N (approximately $N\geq 20$). To achieve mean errors less than 0.25cm or 0.20cm over the entire dataset with PLS, at least 8 or 18 training samples, respectively, must be used.

Conclusion:

The results of this study indicate that PLS shows potential as an efficient (few image acquisitions) and accurate (2-3mm) intra-fraction lung tumor motion modeling technique. Future work will focus on investigating methods for and consequences of non-random training sample selection.